

Bulletin of exercises n°5: Energy balance in MHD. The energy equation.

1. The kinetic energy equation:

By scalar multiplication of the momentum equation (i.e., Navier-Stokes equation including Lorentz' force) with the velocity field and after integrating in a material region Ω_t we obtain an integral balance equation for the kinetic energy of the plasma contained in Ω_t .

Show that the time variation of the total kinetic energy contained in the material region, viz. $\dot{\mathcal{K}}(\Omega_t)$, is given by

$$\frac{d}{dt} \int_{\Omega_t} \frac{1}{2} \rho \|\mathbf{v}\|^2 + \int_{\Omega_t} \hat{\boldsymbol{\sigma}} : \hat{\mathbf{D}} = \int_{\Omega_t} \rho \mathbf{g} \cdot \mathbf{v} + \oint_{\partial\Omega_t} \mathbf{v} \cdot \hat{\boldsymbol{\sigma}} \mathbf{n} + \int_{\Omega_t} \mathbf{v} \cdot \frac{\mathbf{j} \wedge \mathbf{B}}{c} \quad (1.a)$$

or

$$\dot{\mathcal{K}}(\Omega_t) + \mathcal{W}^{\text{def}}(\Omega_t) = \mathcal{W}^{\text{vol}}(\Omega_t) + \mathcal{W}^{\text{sur}}(\partial\Omega_t) + \int \mathbf{v} \cdot \frac{\mathbf{j} \wedge \mathbf{B}}{c} \quad (1.b)$$

Here $\hat{\boldsymbol{\sigma}}$ is the stress tensor and $\hat{\mathbf{D}}$ is the deformation tensor (i.e., the symmetric part of the gradient-of-velocity tensor). Further, $\mathcal{W}^{\text{def}}(\Omega_t)$ is the deformation power, $\mathcal{W}^{\text{vol}}(\Omega_t)$ is the power exerted by the long-range forces –volume forces– on the plasma inside Ω_t and $\mathcal{W}^{\text{sur}}(\partial\Omega_t)$ is the power exerted by the contact forces –surface forces– on the system through its boundary $\partial\Omega_t$.

- What is the physical meaning of the integral $\int_{\Omega_t} \mathbf{v} \cdot (\mathbf{j} \wedge \mathbf{B})/c$?
- Show that under some restriction (which one?), the power exerted by the long-range forces on the plasma contained in Ω_t can be expressed as minus the rate of change of the gravitational potential energy, viz. $\mathcal{W}^{\text{vol}}(\Omega_t) = -\dot{V}(\Omega_t)$.
- Separate in the integral $\mathcal{W}^{\text{def}}(\Omega_t) = \int_{\Omega_t} \hat{\boldsymbol{\sigma}} : \hat{\mathbf{D}}$ the ‘net deformation power’ (i.e., the ‘useful power’) from the power that irreversibly goes into thermal energy through viscous effects.

2. Balance for the kinetic and (electro)magnetic energy budget of a MHD-plasma.

Combining the integral expression of Poynting's theorem for a material region Ω_t [Eq. (4) in bulletin 3] with the kinetic energy theorem derived in exercise 1 [Eq. (1) in this bulletin] we can obtain an expression for the kinetic plus (electro)magnetic energy budget of a MHD-plasma.

- Express the source/sink term appearing in Poynting's equation as $-\mathbf{v} \cdot (\mathbf{j} \wedge \mathbf{B})/c - \|\mathbf{j}\|^2/\sigma_e$.
- Add together the balance equations for the (electro)magnetic and for the kinetic energy of the plasma contained in Ω_t .
- Discuss what we can understand as ‘dynamo’ and ‘motor’ from the resulting balance equation.

3. The so-called *First Principle of Thermodynamics* for a MHD-plasma.

From the integral expression of the principle of energy conservation in a MHD-plasma (without chemical or nuclear reactions) we can obtain an integral balance equation for the internal –or ‘thermal’– energy $U(\Omega_t)$.

- Use Poynting’s theorem (for a material region) along with the theorem for the kinetic energy to show that

$$\frac{d}{dt} \int_{\Omega_t} \rho \epsilon = \int_{\Omega_t} \hat{\boldsymbol{\sigma}} : \hat{\mathbf{D}} - \oint_{\partial\Omega_t} \boldsymbol{\mathcal{F}} \cdot \mathbf{n} + \int_{\Omega_t} \frac{\|\mathbf{j}\|^2}{\sigma_e}, \quad (2)$$

where $\epsilon(\mathbf{x}, t)$ is the specific internal energy (i.e., per unit mass) and $\boldsymbol{\mathcal{F}}(\mathbf{x}, t)$ is the heat flux density vector.

- Obtain a differential equation from the integral expression (2). This equation is the local or differential form of the *First Principle of Thermodynamics* for a MHD-plasma.

4. Energy equation in the (p, T) representation.

Starting from the *First Principle of Thermodynamics* in differential form, show that the energy equation for a MHD-plasma which is a Newtonian fluid can be written in terms of the thermodynamic variables pressure and temperature in the form

$$\rho c_p \frac{DT}{Dt} - \alpha T \frac{Dp}{Dt} = \Phi_v + \Phi_m - \operatorname{div} \boldsymbol{\mathcal{F}}, \quad (3)$$

where Φ_v and Φ_m are, respectively, the viscous and the Ohmic dissipation functions, α is the coefficient of thermal expansion and c_p is the specific heat at constant pressure.